

Non-deterministic semantics for modal logic

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Introduction

Introduction

Motivations:

- philosophical: do possible worlds really exist?¹
- finite models: reasoning about decidability/complexity
- possible application of SAT-solvers

¹John T. Kearns. “Modal Semantics without Possible Worlds”. In: *J. Symb. Log.* 46.1 (1981), pp. 77–86.

Preliminaries

Modal language

Definition

Consider a countable set of propositional variables $Prop = \{p_i \mid i < \omega\}$. Then \mathcal{L} is defined as follows:

$$\mathcal{L} = p_i \mid \varphi \wedge \psi \mid \varphi \vee \psi \mid \neg\varphi \mid \Box\varphi$$

where $p_i \in Prop, \varphi, \psi \in \mathcal{L}$.

Nmatrices

A Nmatrix M for \mathcal{L} is a triple of the form $\langle \mathcal{V}, \mathcal{D}, \mathcal{O} \rangle$, where

- \mathcal{V} is a set of *truth values*
- $\mathcal{D} \subseteq \mathcal{V}$ is a set of *designated truth values*
- \mathcal{O} is a function assigning a *truth table* $\mathcal{V}^n \rightarrow P(\mathcal{V}) \setminus \{\emptyset\}$ to every n -ary connective \diamond of \mathcal{L}

In the context of Nmatrix $M = \langle \mathcal{V}, \mathcal{D}, \mathcal{O} \rangle$, we often denote $\mathcal{O}(\diamond)$ by $\tilde{\diamond}$.²

²Lahav and Zohar, “Effective Semantics for the Modal Logics K and KT via Non-deterministic Matrices”.

Example of Nmatrix for \mathcal{K}

Definition

Nmatrix $M_{\mathcal{K}} = \langle \mathcal{V}, \mathcal{D}, \mathcal{O} \rangle$, with $\mathcal{V} = \{t, f, F, T\}$ $\mathcal{D} = \{t, T\}$ and where \mathcal{O} is defined by the following tables:

$x \tilde{\wedge} y$	T	t	F	f	$x \tilde{\vee} y$	T	t	F	f	x	$\tilde{\neg}x$	x	$\tilde{\square}x$
T	\mathcal{D}	\mathcal{D}	$\overline{\mathcal{D}}$	$\overline{\mathcal{D}}$	T	\mathcal{D}	\mathcal{D}	\mathcal{D}	\mathcal{D}	T	$\overline{\mathcal{D}}$	T	\mathcal{D}
t	\mathcal{D}	\mathcal{D}	$\overline{\mathcal{D}}$	$\overline{\mathcal{D}}$	t	\mathcal{D}	\mathcal{D}	\mathcal{D}	\mathcal{D}	t	$\overline{\mathcal{D}}$	t	$\overline{\mathcal{D}}$
F	$\overline{\mathcal{D}}$	$\overline{\mathcal{D}}$	$\overline{\mathcal{D}}$	$\overline{\mathcal{D}}$	F	\mathcal{D}	\mathcal{D}	$\overline{\mathcal{D}}$	$\overline{\mathcal{D}}$	F	\mathcal{D}	F	\mathcal{D}
f	$\overline{\mathcal{D}}$	$\overline{\mathcal{D}}$	$\overline{\mathcal{D}}$	$\overline{\mathcal{D}}$	f	\mathcal{D}	\mathcal{D}	$\overline{\mathcal{D}}$	$\overline{\mathcal{D}}$	f	\mathcal{D}	f	$\overline{\mathcal{D}}$

The intuition behind these truth-values is the following:

- $v(\varphi) = f$ if φ doesn't hold in w and doesn't hold in some possible world;
- $v(\varphi) = t$ if φ holds in w but doesn't hold in some possible world;
- $v(\varphi) = F$ if φ doesn't hold in w , but holds in all possible worlds;
- $v(\varphi) = T$ if φ holds in w and holds in all possible worlds;

Legal valuations

Given $\mathcal{F} \subseteq \mathcal{L}$, then an \mathcal{F} -valuation $v : \mathcal{F} \rightarrow \mathcal{V}$ is *M-legal* if $v(\varphi) \in \text{pos-val}(\varphi, M, v)$ for every formula $\varphi \in \mathcal{F}$ whose immediate subformulas are contained in \mathcal{F} , where $\text{pos-val}(\varphi, M, v)$ is defined by:

- 1 $\text{pos-val}(p, M, v) = \mathcal{V}$ for every atomic formula p .
- 2 $\text{pos-val}(\diamond(\psi_1, \dots, \psi_n), M, v) = \tilde{\diamond}(v(\psi_1), \dots, v(\psi_n))$ for every non-atomic formula $\diamond(\psi_1, \dots, \psi_n)$.

Definitions of \models and \vdash

Definition

Let \mathcal{V} be the set of truth-values and its proper subset \mathcal{D} – the set of *designated values*. Consider a (possibly non-total) valuation $v : \mathcal{L} \rightarrow \mathcal{V}$ and a formula $\varphi \in \text{Dom}(v) \subseteq \mathcal{L}$, then we write $v \models_{\mathcal{D}} \varphi$, if $v(\varphi) \in \mathcal{D}$. For $\Sigma \subseteq \text{Dom}(v)$ we write $v \models_{\mathcal{D}} \Sigma$ if $v \models_{\mathcal{D}} \varphi$ for any $\varphi \in \Sigma$.

Definition

For a set \mathbb{V} of valuations and sets $L, R \subseteq \mathcal{L}$ of formulas. We write $L \vdash_{\mathcal{D}}^{\mathbb{V}} R$ if for every $v \in \mathbb{V}$, $v \models_{\mathcal{D}} L$ implies $v \models_{\mathcal{D}} \varphi$ for some $\varphi \in R$. We write $\models_{\mathcal{T}}$ and $\vdash_{\mathcal{T}}^{\mathbb{V}}$ instead of $\models_{\{\mathcal{T}\}}$ and $\vdash_{\{\mathcal{T}\}}^{\mathbb{V}}$.

Counterexample

Consider formula $\neg\Box(p \wedge q) \vee (\Box p \wedge \Box q)$ and valuation:

- $v(p) = v(q) = \mathbf{f}$
- $v(p \wedge q) = \mathbf{F}$
- $v(\Box p) = v(\Box q) = v(\Box p \wedge \Box q) = \mathbf{F}$
- $v(\Box(p \wedge q)) = \mathbf{T}$
- $v(\neg\Box(p \wedge q)) = \mathbf{F}$
- $v(\neg\Box(p \wedge q) \vee (\Box p \wedge \Box q)) = \mathbf{F}$

Level valuations

Definition (Level valuations)

- $\mathbb{V}_K^{\mathcal{F},0} = \{v \mid v \text{ is a } M_K\text{-legal } \mathcal{F}\text{-valuation}\}$
- $\mathbb{V}_K^{\mathcal{F},m+1} = \left\{ v \in \mathbb{V}_K^{\mathcal{F},m} \mid \forall \varphi \in \mathcal{F}. v^{-1}[\mathbf{TF}] \vdash_{\mathcal{D}}^{\mathbb{V}_K^{\mathcal{F},m}} \varphi \implies v(\varphi) \in \mathbf{TF} \right\}$
for $m \geq 0$.

G calculus

$$(\text{WEAK}) \frac{\Gamma \Rightarrow \Delta}{\Gamma, \Gamma' \Rightarrow \Delta, \Delta'} \quad (\text{ID}) \frac{}{\Gamma, \varphi \Rightarrow \varphi, \Delta} \quad (\text{CUT}) \frac{\Gamma, \varphi \Rightarrow \Delta \quad \Gamma \Rightarrow \varphi, \Delta}{\Gamma \Rightarrow \Delta}$$

$$(\neg \Rightarrow) \frac{\Gamma \Rightarrow \varphi, \Delta}{\Gamma, \neg \varphi \Rightarrow \Delta} \quad (\Rightarrow \neg) \frac{\Gamma, \varphi \Rightarrow \Delta}{\Gamma \Rightarrow \neg \varphi, \Delta} \quad (\supset \Rightarrow) \frac{\Gamma \Rightarrow \varphi, \Delta \quad \Gamma, \psi \Rightarrow \Delta}{\Gamma, \varphi \supset \psi, \Delta}$$

$$(\Rightarrow \supset) \frac{\Gamma, \varphi \Rightarrow \psi, \Delta}{\Gamma \Rightarrow \varphi \supset \psi, \Delta} \quad (\wedge \Rightarrow) \frac{\Gamma, \varphi, \psi \Rightarrow \Delta}{\Gamma, \varphi \wedge \psi \Rightarrow \Delta} \quad (\Rightarrow \wedge) \frac{\Gamma \Rightarrow \varphi, \Delta \quad \Gamma \Rightarrow \psi, \Delta}{\Gamma \Rightarrow \varphi \wedge \psi, \Delta}$$

$$(\vee \Rightarrow) \frac{\Gamma, \varphi \Rightarrow \Delta \quad \Gamma, \psi \Rightarrow \Delta}{\Gamma, \varphi \vee \psi \Rightarrow \Delta} \quad (\Rightarrow \vee) \frac{\Gamma \Rightarrow \varphi, \psi, \Delta}{\Gamma \Rightarrow \varphi \vee \psi, \Delta}$$

Modal calculi

$$(K) \frac{\Gamma \Rightarrow \varphi}{\Box \Gamma \Rightarrow \Box \varphi}$$

$$(T) \frac{\varphi, \Gamma \Rightarrow \Delta}{\Box \varphi, \Gamma \Rightarrow \Delta}$$

$$(4) \frac{\Box \Gamma_1, \Gamma_2 \Rightarrow \varphi}{\Box \Gamma_1, \Box \Gamma_2 \Rightarrow \Box \varphi}$$

We call $G_K = G + K$, $G_{K4} = G + 4$, $G_{S4} = G + T + 4$

Derivability

Definition

Given a sequent $\Gamma \Rightarrow \Delta$, by $\vdash_{G_{S4}}^{\mathcal{F},m} \Gamma \Rightarrow \Delta$ we mean that there is a derivation of the sequent $\Gamma \Rightarrow \Delta$ in G_{S4} with 4-depth of m , where 4-depth of the derivation denotes the maximal number of (4) rule applications used in any branch of the derivation. For an ω -sequent $L \Rightarrow R$ we write $\Vdash_{G_{S4}}^{\mathcal{F},m} L \Rightarrow R$ if for some finite sub-sequent $\Gamma \Rightarrow \Delta$ of $L \Rightarrow R$,

$$\vdash_{G_{S4}}^{\mathcal{F},m} \Gamma \Rightarrow \Delta.$$

Results for S4

Nmatrix for S4

Definition

Nmatrix $M_{S4} = \langle \mathcal{V}, \mathcal{D}, \mathcal{O} \rangle$, with $\mathcal{V} = \{t, f, T\}$ $\mathcal{D} = \{t, T\}$ and where \mathcal{O} is defined by the following tables:

$x \tilde{\wedge} y$	T	t	f	$x \tilde{\vee} y$	T	t	f	x	$\tilde{\neg}x$	x	$\tilde{\Box}x$
T	\mathcal{D}	\mathcal{D}	{f}	T	\mathcal{D}	\mathcal{D}	\mathcal{D}	T	{f}	t	{f}
t	\mathcal{D}	\mathcal{D}	{f}	t	\mathcal{D}	\mathcal{D}	\mathcal{D}	t	{f}	f	{f}
f	{f}	{f}	{f}	f	\mathcal{D}	\mathcal{D}	{f}	f	\mathcal{D}	T	{T}

Level valuations for M_{S4}

Definition (Level valuations)

- $\mathbb{V}_{S4}^{\mathcal{F},0} = \{v \mid v \text{ is a } M_{S4}\text{-legal } \mathcal{F}\text{-valuation}\}$
- $\mathbb{V}_{S4}^{\mathcal{F},m+1} = \left\{ v \in \mathbb{V}_{S4}^{\mathcal{F},m} \mid \forall \varphi \in \mathcal{F}. v^{-1}[\mathbf{T}] \vdash_{\mathcal{D}}^{\mathbb{V}_{S4}^{\mathcal{F},m}} \varphi \implies v(\varphi) = \mathbf{T} \right\}$
for $m > 0$.

Soundness

Lemma (Soundness for (T))

Suppose that $\Delta \cup \Gamma \cup \{\varphi, \Box\varphi\} \subseteq \mathcal{F}$ and $\varphi, \Gamma \vdash_{\mathcal{D}}^{\mathbb{V}_{S4}^{\mathcal{F},m}} \Delta$. Then $\Box\varphi, \Gamma \vdash_{\mathcal{D}}^{\mathbb{V}_{S4}^{\mathcal{F},m}} \Delta$.

Lemma (Soundness for (4))

Suppose that $\Box\Gamma_1 \cup \Gamma_2 \cup \Box\Gamma_2 \cup \{\varphi, \Box\varphi\} \subseteq \mathcal{F}$ and $\Box\Gamma_1, \Gamma_2 \vdash_{\mathcal{D}}^{\mathbb{V}_{S4}^{\mathcal{F},m-1}} \varphi$. Then $\Box\Gamma_1, \Box\Gamma_2 \vdash_{\mathcal{D}}^{\mathbb{V}_{S4}^{\mathcal{F},m}} \Box\varphi$. For $m > 0$.

Completeness

For completeness one should provide a countermodel for an ω -sequence, that is not derivable.

Definition (Maximal and consistent ω -sequent)

Let $\mathcal{F} \subseteq \mathcal{L}$ and $m \geq 0$. A \mathcal{F} - ω -sequent $L \Rightarrow R$ is called:

- ① \mathcal{F} -maximal if $\mathcal{F} \subseteq L \cup R$.
- ② $\langle G_{S4}, \mathcal{F}, m \rangle$ -consistent if $\not\vdash_{G_{S4}}^{\mathcal{F}, m} L \Rightarrow R$.
- ③ $\langle G_{S4}, \mathcal{F}, m \rangle$ -maximal-consistent (in short, $\langle G_{S4}, \mathcal{F}, m \rangle$ -max-con) if it is \mathcal{F} -maximal and $\langle G_{S4}, \mathcal{F}, m \rangle$ -consistent.

Countermodel

Definition

We denote $\mathbb{B}_{\mathcal{F}}^X = \{\psi \in \mathcal{F} \mid \Box\psi \in X\}$.

Then

$$v(\mathcal{F}, L \Rightarrow R, m) = \begin{cases} m = 0 \\ \lambda\varphi. \begin{cases} \mathbf{T}, & \varphi \in L \wedge \Box\varphi \notin R \\ \mathbf{t}, & \varphi \in L \wedge \Box\varphi \in R \\ \mathbf{f}, & \varphi \in R \end{cases} \end{cases} \quad \begin{cases} m > 0 \\ \lambda\varphi. \begin{cases} \mathbf{T}, & \varphi \in L \wedge \Vdash_{\text{GS4}}^{\mathcal{F}, m-1} \Box\mathbb{B}_{\mathcal{F}}^L \Rightarrow \varphi \\ \mathbf{t}, & \varphi \in L \wedge \not\vdash_{\text{GS4}}^{\mathcal{F}, m-1} \Box\mathbb{B}_{\mathcal{F}}^L \Rightarrow \varphi \\ \mathbf{f}, & \varphi \in R \end{cases} \end{cases}$$

Completeness

Theorem (Completeness)

Let $\mathcal{F} \subseteq \mathcal{L}$ be closed under subformulas. Suppose $L \Rightarrow R$ is a $\langle G_{S4}, \mathcal{F}, m+1 \rangle$ -max-con ω -sequent, then there is a valuation $v \in \mathbb{V}_{S4}^{\mathcal{F}, m}$, such that $v \not\models_{\mathcal{D}} L \Rightarrow R$.

Completeness lemmas

Lemma

Let $\mathcal{F} \subseteq \mathcal{L}$ be closed under subformulas. Given $L \Rightarrow R$ is a $\langle \mathbb{G}_{S4}, \mathcal{F}, 0 \rangle$ -max-con ω -sequent. Then $v(\mathcal{F}, L \Rightarrow R, 0) \in \mathbb{V}_{S4}^{\mathcal{F}, 0}$.

Lemma

Let $\mathcal{F} \subseteq \mathcal{L}$ be closed under subformulas. Given $L \Rightarrow R$ is a $\langle \mathbb{G}_{S4}, \mathcal{F}, m \rangle$ -max-con ω -sequent. Then $v(\mathcal{F}, L \Rightarrow R, m) \in \mathbb{V}_{S4}^{\mathcal{F}, 0}$.

Lemma

Let $\mathcal{F} \subseteq \mathcal{L}$ be closed under subformulas. Given $L \Rightarrow R$, a $\langle \mathbb{G}_{S4}, \mathcal{F}, m \rangle$ -max-con ω -sequent. If for any \mathcal{F} - ω -sequent $L' \Rightarrow R'$ and for any $k < m$ we have $L' \vdash_{\mathcal{D}}^{\mathbb{V}_{S4}^{\mathcal{F}, k}} R'$ implies $\Vdash_{\mathbb{G}_{S4}}^{\mathcal{F}, k} L' \Rightarrow R'$. Then $v(\mathcal{F}, L \Rightarrow R, m) \in \mathbb{V}_{S4}^{\mathcal{F}, m}$.

Effectiveness

Algorithm

Algorithm 1 Deciding $\Gamma \vdash_{\mathcal{D}}^{\forall S4} \varphi$.

- 1: $\mathcal{F} \leftarrow \text{sub}(\Gamma \cup \{\varphi\})$
 - 2: $m \leftarrow 3^{|\mathcal{F}|}$
 - 3: **for** $v \in \mathbb{V}_{S4}^{\mathcal{F}, m}$ **do**
 - 4: **if** $v \models_{\mathcal{D}} \Gamma$ and $v \not\models_{\mathcal{D}} \varphi$ **then**
 - 5: **return** (“NO”, v)
 - 6: **return** “YES”
-

Lemma

For a finite set \mathcal{F} of formulas, $(\bigcap_{i < \omega} \mathbb{V}_{S4}^{\mathcal{F}, i} =) \mathbb{V}_{S4}^{\mathcal{F}} = \mathbb{V}_{S4}^{\mathcal{F}, 3^{|\mathcal{F}|}}$.

Extension

The algorithm is correct, but in applications we might need a construction of the countermodel. If $\Gamma \not\vdash_{\mathcal{D}}^{\mathbb{V}_{S4}} \varphi$, then there is a $u \in \mathbb{V}_{S4}$, such that $u \models_{\mathcal{D}} \Gamma$ and $u \not\models_{\mathcal{D}} \varphi$. However, we don't know anything about the connection between u and v from the algorithm output.

This motivates us to investigate the existence of a total extension $v' \in \mathbb{V}_{S4}$, such that $v'|_{\mathcal{F}} = v$.

Kripke models correspondence

Kripke models

Definition

Given $\mathcal{F} \subseteq \mathcal{L}$ is closed under subformula and $v \in \mathbb{V}_K^{\mathcal{F}}$ and a pointed Kripke model $\langle \mathfrak{M}, x \rangle$. We write $\langle \mathfrak{M}, x \rangle \Vdash \langle \mathcal{F}, v \rangle$ if for any $\varphi \in \mathcal{F}$

- $v(\varphi) = \mathbf{t}$ iff. $\mathfrak{M}, x \models \varphi$ and there is an $y \in W$, such that xRy and $\mathfrak{M}, y \not\models \varphi$
- $v(\varphi) = \mathbf{f}$ iff. $\mathfrak{M}, x \not\models \varphi$ and there is an $y \in W$, such that xRy and $\mathfrak{M}, y \not\models \varphi$
- $v(\varphi) = \mathbf{T}$ iff. $\mathfrak{M}, x \models \varphi$ and for any $y \in W$ such that $xRy, \mathfrak{M}, y \models \varphi$
- $v(\varphi) = \mathbf{F}$ iff. $\mathfrak{M}, x \not\models \varphi$ and for any $y \in W$ such that $xRy, \mathfrak{M}, y \models \varphi$

Summary

Summary

- completeness and soundness were established
- does extension exist?
- how to build a kripke model, corresponding to a valuation?



Kearns, John T. “Modal Semantics without Possible Worlds”. In: *J. Symb. Log.* 46.1 (1981), pp. 77–86.



Lahav, Ori and Yoni Zohar. “Effective Semantics for the Modal Logics K and KT via Non-deterministic Matrices”. In: *Automated Reasoning - 11th International Joint Conference, IJCAR 2022, Haifa, Israel, August 8-10, 2022, Proceedings*. Ed. by Jasmin Blanchette, Laura Kovács, and Dirk Pattinson. Vol. 13385. Lecture Notes in Computer Science. Springer, 2022, pp. 468–485. DOI: [10.1007/978-3-031-10769-6_28](https://doi.org/10.1007/978-3-031-10769-6_28). URL: https://doi.org/10.1007/978-3-031-10769-6_28.